# Characterizing Trees for Lambda-mu Terms

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Abstract. We give the conditions to characterize Böhm tree structures which represent terms of the Lambda-mu calculus. This result answers a question stated in Saurin's FLOPS paper.

#### Introduction 1

In [3], Saurin extends the Böhm trees and the expanded Böhm trees, called Nakajima trees in [3], to the  $\Lambda\mu$ -terms. It is a beautiful theoretical result that we can obtain the (expanded) Böhm trees for  $A\mu$  just by extending the bound of lengths of prefixes and arguments to  $\omega^2$ , whereas it is  $\omega$  for the  $\lambda$ -calculus. An open problem stated in [3] is on characterization of the tree structures which represent some  $A\mu$ -terms. For the  $\lambda$ -calculus, this problem was solved by Nakajima in [1], where he gave some conditions for the expanded Böhm trees and showed that they give the exact characterization of trees which represents some  $\lambda$ -terms.

In this paper, we extended Nakajima's result to  $A\mu$ , and solve Saurin's open problem. The idea of the characterizing conditions are almost the same as [1], and they require that the information of each node is computable, and that all of nodes except for a finite part are obtained by  $\eta$ -expansion. The conditions for  $A\mu$ -calculus become much more complicated than the case of  $\lambda$ -calculus, because we have to manage the correspondence of  $\mu$ -variables in prefixes and bodies.

#### $\mathbf{2}$ Expanded Böhm Trees of $\Lambda\mu$ -Terms

**Definition 1.** The  $A\mu$ -terms are defined as follows:

$$t, s ::= x \mid \lambda x.t \mid (t)s \mid \mu \alpha.t \mid (t)\alpha$$

 $\Sigma_{\Lambda\mu}$  is the set of all  $\Lambda\mu$ -terms.  $\Sigma_{\Lambda\mu}^c$  is the set of all closed  $\Lambda\mu$ -terms. In this paper, we always suppose every  $A\mu$ -term is closed with respect to  $\mu$ -variables. The reduction rules for the  $\Lambda\mu$ -calculus are the following.

$$\begin{aligned} (\lambda x.t)s \to_{\beta_T} t[x := s] \\ (\mu \alpha.t)\beta \to_{\beta_S} t[\alpha := \beta] \\ \mu \alpha.(t)\alpha \to_{\eta_S} t \\ \mu \alpha.t \to_{\text{fst}} \lambda x.\mu \alpha.t[(v)\alpha := (v)x\alpha] \end{aligned} \qquad (\alpha \notin FV(t))$$

As in [3], the stream head normal form (shnf) of a  $\Lambda\mu$ -term is

$$\lambda \boldsymbol{x}^{0} \boldsymbol{\mu} \boldsymbol{\alpha}^{0} \cdots \boldsymbol{\lambda} \boldsymbol{x}^{n-1} \boldsymbol{\mu} \boldsymbol{\alpha}^{n-1} . (\boldsymbol{y}) \boldsymbol{t}^{0} \boldsymbol{\beta}^{0} \cdots \boldsymbol{t}^{m-1} \boldsymbol{\beta}^{m-1},$$

where each  $x^i$  and  $t^j$  are finite sequences of  $\lambda$ -variables and  $\Lambda\mu$ -terms. For simplicity, we write  $t \to_h^* h$  for the head reduction followed by zero- or one-step  $\eta_s$ -reduction to a shuff h.

Saurin showed in [3] that the Böhm trees are adapted to the  $\Lambda\mu$ -calculus by extending the width from  $\omega$  to  $\omega^2$ . We consider fully  $\eta$ -expanded form, and hence each node uniformly has  $\omega^2$  children. We call such trees *expanded Böhm* trees for the  $\Lambda\mu$ -calculus, which are originally defined by coinduction as follows:

$$\mathfrak{T} ::= \bot \mid \Lambda(x_i)_{i \in \omega^2} . (y)(\mathfrak{T}_j)_{j \in \omega^2},$$

where  $\Lambda(x_i)_{i \in \omega^2}(y)$  is called a prefix. Positions of nodes in trees are expressed by finite lists of elements of  $\omega^2$ .

**Definition 2.**  $\Delta$  is the set of all finite lists consisting of elements of  $\omega^2$ , that is,  $[] \in \Delta$  (empty list), and if  $\delta \in \Delta$  and  $\mu \in \omega^2$ , then  $\delta :: \mu \in \Delta$ .  $\delta \leq \delta'$  means that  $\delta$  is an initial segment of  $\delta'$ .  $\delta < \delta'$  means  $\delta \leq \delta'$  and  $\delta \neq \delta'$ .

By renaming bound variables, we suppose that bound  $\lambda$ -variables in prefixes are uniformly indexed by an element of  $\Delta \times \omega^2$  depending on the position where they are abstracted, that is, we define the set of all bound  $\lambda$  variables as  $BV_{\lambda} = \{x_{\delta}^{\mu} \mid \delta \in \Delta, \mu \in \omega^2\}$ , and the prefix at the position  $\delta$  is fixed as  $\lambda x_{\delta}^0 x_{\delta}^1 \cdots (y)$ with some head variable y, where  $x_{\delta}^i = x_{\delta}^{\omega \cdot i} x_{\delta}^{\omega \cdot i+1} x_{\delta}^{\omega \cdot i+2} \cdots$ . We use this notation  $x_{\delta}^i$  in the following, and another notation  $x_{\delta}^{i,<j} = x_{\delta}^{\omega \cdot i} x_{\delta}^{\omega \cdot i+1} \cdots x_{\delta}^{\omega \cdot i+j-1}$ .

In order to consider the fst-reduction, we have to remember some information on bound  $\mu$ -variables during the definition of the expanded Böhm trees of  $\Lambda\mu$ terms. In the following definition,  $\phi(\delta, k) = l$  means that the prefix of the shuff at the position  $\delta$  contains a subterm of the form  $\cdots \lambda \boldsymbol{x}_{\delta}^{k,<l} \mu \alpha_{\delta}^{k} \cdots$ . Similarly to  $BV_{\lambda}$ , we fix the name of bound  $\mu$ -variables depending on the position where they are abstracted. The set of bound  $\mu$ -variables is  $BV_{\mu} = \{\alpha_{\delta}^{k} \mid \delta \in \Delta, k \in \omega\}$ .

Then, names of head variables at each position and existence of shnf are sufficient to characterize expanded Böhm trees.

**Definition 3.** An expanded Böhm tree for  $A\mu$ -calculus is a mapping  $\mathfrak{T}$  from  $\Delta$  to  $BV_{\lambda} \cup \{\bot\}$  such that  $\mathfrak{T}(\delta) = \bot$  and  $\delta' > \delta$  imply  $\mathfrak{T}(\delta') = \bot$ . The set of the expanded Böhm trees is denoted by  $A\mu$ - $\mathfrak{BT}^+$ . We write  $\mathfrak{T}(\delta) \uparrow$  to mean  $\mathfrak{T}(\delta) = \bot$ , and  $\mathfrak{T}(\delta) \downarrow$  otherwise.

We can intuitively understand this definition as follows:  $\mathfrak{T}(\delta) = x_{\delta'}^{\mu}$  means that the head variable in the prefix at  $\delta$  is the  $\mu$ -th variable in the prefix at  $\delta'$ , and  $\mathfrak{T}(\delta) \uparrow$  means that the node at  $\delta$  is  $\bot$ , which represents an unsolvable term, and we suppose that all nodes below  $\bot$  are indexed by  $\bot$  for simplicity.

**Definition 4.** For  $t \in \Sigma_{A\mu}^c$ , we define the *expanded Böhm tree*  $\mathfrak{BT}_t^+$  of t with auxiliary partial mappings  $t_{(\cdot)} : \Delta \to \Sigma_{A\mu} \cup \{\bot\}$  and  $\phi_t : \Delta \times \omega \longrightarrow \omega$  as follows:

- (0)  $\mathfrak{T}$  is recursive, and there exist the following five partial recursive mappings:
- $\begin{aligned} &- \mathsf{p}_{\lambda}^{\mathfrak{T}}, \mathsf{b}_{\mu}^{\mathfrak{T}} : \Delta \longrightarrow \omega, \text{ the domains of which are } \{\delta \in \Delta \mid \mathfrak{T}(\delta) \downarrow\}, \\ &- \mathsf{p}_{\lambda}^{\mathfrak{T}}, \mathsf{b}_{\lambda}^{\mathfrak{T}} : \Delta \times \omega \longrightarrow \omega, \text{ and } \mathsf{Bd}_{\mu}^{\mathfrak{T}} : \Delta \times \omega \longrightarrow \Delta \times \omega, \text{ the domains of which are } \{\langle \delta, k \rangle \in \Delta \times \omega \mid \mathfrak{T}(\delta) \downarrow\}. \end{aligned}$   $\begin{aligned} &(1) \ \mathfrak{T}(\delta) = x_{\delta'}^{\mu} \Longrightarrow \delta' \leq \delta \text{ and } \mathsf{Bd}_{\mu}^{\mathfrak{T}}(\delta, k) = \langle \delta', k' \rangle \Longrightarrow \delta' \leq \delta \\ &(2) \ \mathfrak{T}(\delta :: (\omega \cdot k + l)) = x_{\delta'}^{\omega \cdot k' + l'} \& l < \mathsf{b}_{\lambda}^{\mathfrak{T}}(\delta, k) \Longrightarrow l' < \mathsf{p}_{\lambda}^{\mathfrak{T}}(\delta', k') \\ &(3) \ \mathsf{Bd}_{\mu}^{\mathfrak{T}}(\delta, k) = \langle \delta', k' \rangle \& k < \mathsf{b}_{\mu}^{\mathfrak{T}}(\delta) \Longrightarrow k' < \mathsf{p}_{\mu}^{\mathfrak{T}}(\delta') \\ &(4) \ \mathsf{Bd}_{\mu}^{\mathfrak{T}}(\delta, k) = \langle \delta', k' \rangle \& l \geq \mathsf{b}_{\lambda}^{\mathfrak{T}}(\delta, k) \Longrightarrow \\ &- \ \mathfrak{T}(\delta :: (\omega \cdot k + l)) = x_{\delta'}^{\omega \cdot k' + (\mathsf{p}_{\lambda}^{\mathfrak{T}}(\delta') + l \mathsf{b}_{\lambda}^{\mathfrak{T}}(\delta, k)) \\ &- \ \delta'' \geq \delta :: (\omega \cdot k + l) \Longrightarrow \mathfrak{T}(\delta'' :: \mu) = x_{\delta''}^{\mu} \text{ for any } \mu \And \mathsf{p}_{\mu}^{\mathfrak{T}}(\delta'') = 0 \And \mathsf{b}_{\mu}^{\mathfrak{T}}(\delta'') = 0 \\ \end{aligned}$

### Fig. 1. Characterizing Conditions

 $\begin{aligned} &-t_{[]} = t \\ &- \text{ If } t_{\delta} \text{ has no shnf, } \mathfrak{BT}_{t}^{+}(\delta) = \bot, \text{ and } t_{\delta'} \text{ for any } \delta < \delta' \text{ and } \phi_{t}(\delta'', k) \text{ for any } \\ &\delta \leq \delta'' \text{ and } k \in \omega \text{ are undefined.} \\ &- \text{ If } t_{\delta} \rightarrow_{h}^{*} \lambda \boldsymbol{x}_{\delta}^{0, < i_{0}} \mu \alpha_{\delta}^{0} \cdots \lambda \boldsymbol{x}_{\delta}^{n-1, < i_{n-1}} \mu \alpha_{\delta}^{n-1} .(y) \boldsymbol{t}^{0} \alpha_{\delta_{0}}^{j_{0}} \cdots \boldsymbol{t}^{m-1} \alpha_{\delta_{m-1}}^{j_{m-1}}, \text{ then} \end{aligned}$ 

$$\mathfrak{BT}_{t}^{+}(\delta) = y$$

$$\phi_{t}(\delta, k) = \begin{cases} i_{k} & (k < n) \\ 0 & (k \ge n) \end{cases}$$

$$t_{\delta::(\omega \cdot k+l)} = \begin{cases} t_{k}^{l} & (k < m \& \mathbf{t}_{k} = t_{k}^{0} \cdots t_{k}^{i_{k}-1} \& l < i_{k}) \\ x_{\delta_{k}}^{\omega \cdot j_{k} + (\phi_{t}(\delta_{k}, j_{k}) + l - i_{k})} \\ x_{\delta}^{\omega \cdot (k-m+n) + l} & (k < m \& \mathbf{t}_{k} = t_{k}^{0} \cdots t_{k}^{i_{k}-1} \& l \ge i_{k}) \end{cases}$$

Note that  $\delta_k \leq \delta$  holds for  $0 \leq k < m$  since  $\alpha_{\delta_k}^{j_k}$  is a bound  $\mu$ -variable in t.

## **3** Characterization

### 3.1 Characterization of Expanded Böhm Trees for $\Lambda\mu$ -Terms

For each  $\mathfrak{T} \in \Lambda\mu - \mathfrak{BT}^+$ , we consider the conditions in Figure 1. The intuitive meaning of the partial mappings is the following:  $\mathbf{p}_{\mu}^{\mathfrak{T}}(\delta)$  is the number of  $\mu$ abstractions in the prefix of the shnf of  $t_{\delta}$ .  $\mathbf{p}_{\lambda}^{\mathfrak{T}}(\delta, k)$  is the number of  $\lambda$ -abstractions surrounding the k-th  $\mu$ -variable in the prefix of the shnf of  $t_{\delta}$ .  $\mathbf{b}_{\mu}^{\mathfrak{T}}(\delta)$  is the number of  $\mu$ -variables in the body part of the shnf of  $t_{\delta}$ .  $\mathbf{b}_{\lambda}^{\mathfrak{T}}(\delta, k)$  is the number of term arguments delimited by the k-th  $\mu$ -variable in the body part of the shnf of  $t_{\delta}$ .  $\mathbf{b}_{\lambda}^{\mathfrak{T}}$  corresponds to the function  $\phi_t$ .  $\mathsf{Bd}_{\mu}^{\mathfrak{T}}(\delta, k) = \langle \delta', k' \rangle$  means that the k-th  $\mu$ variable in the body part of the shnf of  $t_{\delta}$  is bound at k'-th  $\mu$ -abstraction in the prefix of the shnf of  $t'_{\delta}$ . The conditions are intuitively explained as follows. (1) means that each variable is bound at a position outside of it. (2) and (3) require that, if a variable occurs in a body part of a shnf, it is bound at a prefix which is not in an  $\eta$ -expanded part, which means a part obtained by the  $\eta_S$ -expansion and the fst-reduction. (4) means that, if a  $\lambda$ -variable occurs in an  $\eta$ -expanded part, it is obtained a fst-reduction for a corresponding  $\mu$ -variable, and all of the nodes below it are in  $\eta$ -expanded parts. (5) means that, if a  $\mu$ -variable is in an  $\eta$ -expanded part, there is no  $\lambda$ -variable accompanying the  $\mu$ -variable. (6) means that, if a  $\mu$ -variable occurs in an  $\eta$ -expanded part, the  $\mu$ -variable solution of the nodes below it are in  $\eta$ -expanded parts. (5) means that, if a  $\mu$ -variable is in an  $\eta$ -expanded part, there is no  $\lambda$ -variable accompanying the  $\mu$ -variables following it are obtained by the  $\eta_S$ -expansion.

**Theorem 1.** For  $\mathfrak{T} \in \Lambda \mu - \mathfrak{BT}^+$ , there exists a closed  $\Lambda \mu$ -term t such that  $\mathfrak{T} = \mathfrak{BT}_t^+$  iff  $\mathfrak{T}$  satisfies all of the conditions in Figure 1.

*Proof.* (The detailed proof is in [2].)

Let  $\mathfrak{T} = \mathfrak{BT}_t^+$ . By definition, when  $\mathfrak{T}(\delta) = y$ , we have

$$t_{\delta} \to_{h}^{*} \lambda \boldsymbol{x}_{\delta}^{0, < i_{0}} \mu \alpha_{\delta}^{0} \cdots \mu \alpha_{\delta}^{k-2} \lambda \boldsymbol{x}_{\delta}^{k-1, < i_{k-1}} \mu \alpha_{\delta}^{k-1}.$$
$$(y) t^{0} \cdots t^{j_{0}} \alpha_{\delta_{0}}^{j_{0}} \cdots \alpha_{\delta_{l-2}}^{j_{l-2}} t^{\omega \cdot (l-1)} \cdots t^{\omega \cdot (l-1)+j_{l-1}-1} \alpha_{\delta_{l-1}}^{j_{l-1}}.$$

Then we define the partial mappings in the condition (0) as follows:

$$\begin{split} \mathbf{p}_{\mu}^{\mathfrak{T}}(\delta) &= k & \mathbf{b}_{\mu}^{\mathfrak{T}}(\delta) = l \\ \mathbf{p}_{\lambda}^{\mathfrak{T}}(\delta, n) &= \begin{cases} i_{n} & (n < k) \\ 0 & (n \ge k) \end{cases} & \mathbf{b}_{\lambda}^{\mathfrak{T}}(\delta, n) = \begin{cases} j_{n} & (n < l) \\ 0 & (n \ge l) \end{cases} \\ & \mathsf{Bd}_{\mu}^{\mathfrak{T}}(\delta, n) = \begin{cases} \langle \delta_{n}, j_{n} \rangle & (n < l) \\ \langle \delta, n - l + k \rangle & (n \ge l) \end{cases} \end{split}$$

They are undefined when  $\mathfrak{T}(\delta) \uparrow$ . They are recursive by definition. It is easy to see that  $\mathfrak{T}$  satisfies the conditions (0) through (6).

For the other direction, suppose that  $\mathfrak{T} \in \Lambda \mu - \mathfrak{BT}^+$  satisfies all of the conditions in Figure 1, and we will construct a term  $t^{\mathfrak{T}}$  such that  $\mathfrak{BT}_{t^{\mathfrak{T}}}^+ = \mathfrak{T}$ . In the following, we omit the superscript  $\mathfrak{T}$  for each mapping and term.

We have the encodings of elements of  $\omega$ ,  $\omega^2$ ,  $\Delta$ , BV, and pairs of them in the  $\lambda$ -calculus. These encodings are overlined. By (0), we have  $\lambda$ -representations of  $\mathfrak{T}$  and the five partial recursive functions:  $\overline{\mathfrak{T}}$ ,  $\overline{p_{\mu}}$ ,  $\overline{p_{\lambda}}$ ,  $\overline{b_{\mu}}$ ,  $\overline{b_{\lambda}}$ , and  $\overline{\mathsf{Bd}}_{\mu}$ . Furthermore we can assume the existence of the following  $\lambda$ -term  $\pi$ :

$$\pi \,\overline{\delta} \to_h^* \begin{cases} \lambda z.z & (\mathfrak{T}(\delta) \downarrow) \\ \text{has no hnf} & (\mathfrak{T}(\delta) \uparrow) \end{cases}$$

We define association lists  $L_{\lambda}$  and  $L_{\mu}$  to map correspondences between actual bound variables and their encodings.

$$\begin{split} \overline{\mathsf{init}}_{\lambda} &= \lambda z.z \quad [\langle \delta, \mu \rangle \mapsto y] @L_{\lambda} = \lambda z. (\text{if } z = \overline{x_{\delta}^{\mu}} \text{ then } y \text{ else } Lz \text{ fi}) \\ \overline{\mathsf{init}}_{\mu} &= \lambda z.z \quad [\langle \delta, k \rangle \mapsto \alpha] @L_{\mu} = \lambda pz. (\text{if } p = \langle \overline{\delta}, \overline{k} \rangle \text{ then } (z) \alpha \text{ else } L_{\mu} pz \text{ fi}) \end{split}$$

The term t is recursively defined as follows:

$$\begin{split} t &= \Theta[\overline{]} \overline{\operatorname{init}}_{\lambda} \overline{\operatorname{init}}_{\mu} \\ \Theta \,\overline{\delta} L_{\lambda} L_{\mu} &= \pi \,\overline{\delta} \, (F \overline{\delta} \,\overline{0} \,\overline{0} \,(\overline{\mathfrak{T}} \,\overline{\delta}) L_{\lambda} L_{\mu}) \\ F \overline{\delta} \,\overline{k} \,\overline{l} V L_{\lambda} L_{\mu} &= \begin{cases} G \overline{\delta} \,(\overline{\mathsf{b}}_{\mu} \,\overline{\delta}) \,\overline{0} V L_{\lambda} L_{\mu} & (\mathsf{p}_{\mu}(\delta) \geq k) \\ \mu \alpha. F \overline{\delta} \,\overline{k} + 1 \,\overline{0} V L_{\lambda} ([\langle \delta, k \rangle \mapsto \alpha] @ L_{\mu}) & (\mathsf{p}_{\lambda}(\delta, k) \leq l) \\ \lambda z. F \overline{\delta} \,\overline{k} \,\overline{l} + 1 V ([\langle \delta, \omega \cdot k + l \rangle \mapsto z] @ L_{\lambda}) L_{\mu} & (\text{otherwise}) \end{cases} \\ G \overline{\delta} \,\overline{k} \,\overline{l} V L_{\lambda} L_{\mu} &= \begin{cases} L_{\lambda} V & (k = 0 \& l = 0) \\ L_{\mu} (\overline{\mathsf{Bd}}_{\mu} \,\overline{\delta} \,\overline{k-1}) (G \overline{\delta} \,\overline{k-1} \,(\overline{\mathsf{b}}_{\lambda} \,\overline{\delta} \,\overline{k-1}) V L_{\lambda} L_{\mu}) & (k > 0 \& l = 0) \\ (G \overline{\delta} \,\overline{k} \,\overline{l} - 1 V L_{\lambda} L_{\mu}) (\Theta \overline{\delta} :: (\omega \cdot k + (l - 1)) L_{\lambda} L_{\mu}) & (l > 0) \end{cases} \end{split}$$

Then, we can see that  $\mathfrak{T}(\delta) = \mathfrak{BT}_t^+(\delta)$  for any  $\delta \in \Delta$ .

# 3.2 Free $\lambda$ -Variables

The discussion in the previous subsection can be extended to  $A\mu$ -terms with free  $\lambda$ -variables. We suppose the set of free  $\lambda$ -variables  $FV_{\lambda}$ , which is disjoint from  $BV_{\lambda}$ . The codomain of  $A\mu$ - $\mathfrak{BT}^+$  is extended to  $BV_{\lambda} \cup FV_{\lambda} \cup \{\bot\}$ . We define  $FV_{\lambda}(\mathfrak{T}) = \{z \in FV_{\lambda} \mid \mathfrak{T}(\delta) = z \text{ for some } \delta\}$ , and we require the following additional condition.

(7)  $\#FV_{\lambda}(\mathfrak{T}) < \omega$ 

Then, the encoding of the variables are extended to

$$\overline{y} = \begin{cases} \overline{y} & (y \in BV_{\lambda}) \\ y & (y \in FV_{\lambda}(\mathfrak{T})), \end{cases}$$

which can be defined due to the condition (7). Notice that for any association list  $L_{\lambda}$  of  $\lambda$ -variables and  $y \in FV_{\lambda}$ , we have  $L_{\lambda} y \to_{h}^{*} \overline{\text{init}}_{\lambda} y \to_{h} y$ .

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